Sixth Semester B.Tech. Degree Examination (2013 Scheme)

13.601 ADVANCED CONTROL SYSTEMS (E)

Time: 3 Hours

Max. Marks: 100

PART- A

(Answer all questions. Each question carries 4 marks.)

- 1. What are the advantages of the state space analysis?
- 2. Prove that the set of state variables for a system is not unique.
- 3. Explain Shannon's sampling theorem.
- 4. Write notes on Jump resonance.
- 5. Determine the positive definiteness of

$$A = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 3 & 2 \\ 0 & 2 & 3 \end{bmatrix}$$

(5 X 4 Marks = 20)

PART- B

(Answer any one full question from each module)

Module - I

6. a) Transfer function of a system is

$$\frac{Y(s)}{\bigcup(s)} = \frac{10(s+4)}{s^3 + 4s^2 + 3s}$$

Obtain state space model in the canonical form. Hence determine the eigen values of the system matrix

(10 Marks)

b) Solve

$$\dot{\mathbf{x}} = \begin{bmatrix} 0 & 1 \\ -3 & -2 \end{bmatrix} \mathbf{X}; \qquad \qquad \mathbf{X}(0) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

(10 Marks)

(OR)

7. Consider a system represented by the state equation X = AX

$$is = \begin{bmatrix} e^{-t} + te^{-t} & te^{-t} \\ te^{-t} & e^{-t} - te^{-t} \end{bmatrix}$$

Given State transition matrix

(a) Find a set of states $x_1(0)$ and $X_2(0)$ such that $x_1(2) = 2$

(b) Find system matrix

(20 Marks)

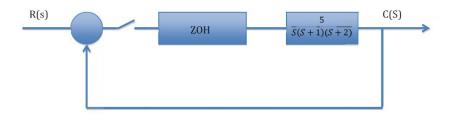
Module-II

8. (a) Solve the Difference equation by use of z-transform method.

$$x(k) - 3x(k-1) + 2x(k-2) = 4^{k}$$

(10 Marks)

(b) Find the step response of the given sampled data system



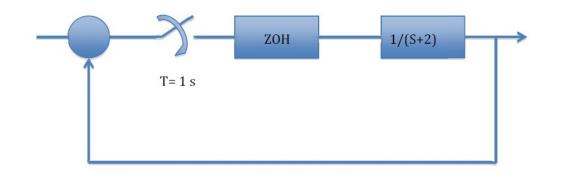
(10 Marks)

(OR)

9. a) Explain how s-plane is mapped into z-plane

(5 Marks)

b) Obtain the pulse transfer function of the sampled data control system. Find output c(k) for r(t) = u(t).

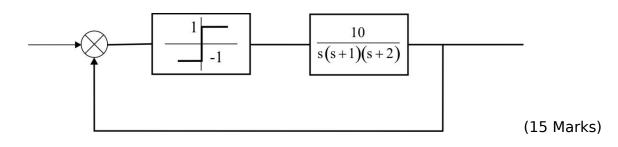


(15Marks)

Module-III

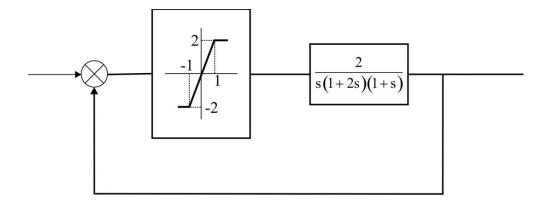
10. a) Explain with diagram different types of nonlinearities (5 Marks)

b) For the non-linear system given below, investigate the possibility of a limit cycle. If limit cycle exists, find its magnitude and frequency.



11. a) Derive the describing function of saturation non-linearity.

(5 Marks) b) For the non-linear system given below, investigate the possibility of a limit cycle. If limit cycle exists, find its magnitude and frequency.



(15 Marks)

Module-IV

12. a) Write notes on singular points

b) A system is described by the following equation:

 $\dot{x}_1 = -x_1 + x_2 + x_1 (x_1^2 + x_2^2)$

$$\dot{x}_2 = -x_1 - x_2 + x_2 (x_1^2 + x_2^2)$$

Determine the stability using Liapunov method.

(15 Marks)

(OR)

13. a) Write notes on phase plane analysis

b) Given

 $\begin{bmatrix} \dot{x_1} \\ \dot{x_2} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

Find a Liapunov function and test the stability

(15 Marks)

(5 Marks)

(5 Marks)